

$$(AB)^{-1} = B^{-1}A^{-1}$$

Last Time we proved $\det(AB) = \det(A)\det(B)$.

Now we will show:

Theorem A^{-1} exists iff $\det(A) \neq 0$

proof (\Leftarrow) Suppose $\det(A) \neq 0$.

Suppose $B = E_k \dots E_1 A$ is in RREF

$$\text{Then } \det(B) = \det(E_k) \dots \det(E_1) \det(A)$$

Since all of these are not zero, then $\det(B) \neq 0$. Thus B has no all-zero rows, and so $B = I$. Therefore

$$A^{-1} = (E_k \dots E_1)^{-1} I = E_1^{-1} E_2^{-1} \dots E_k^{-1}$$

In fact, this is how we usually find the inverse.

(\Rightarrow) Suppose A^{-1} exists. Then $A \cdot A^{-1} = I$

$$\text{so } \det(A A^{-1}) = \det(I)$$

$$\det(A) \det(A^{-1}) = 1$$

Thus $\det(A) \neq 0$ \square

Summary TFAE:

- (a) A is invertible
- (b) $Ax = 0$ has only the trivial solution
- (c) $Ax = b$ has the unique solution $x = A^{-1}b$ (for every b)
- (d) $A \sim I$
- (e) $\det(A) \neq 0$

$$\text{Ch 2 #15a)} \quad A_1^* = \begin{pmatrix} 1 & 0 & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & k_1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ k_2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

compression in x_2 shear in x_2

$SR_i + R_j \rightarrow R_i$ is not allowed

Example of LU-factorization

$$A = \begin{pmatrix} 3 & 1 & 3 \\ 9 & 4 & 10 \\ 6 & -1 & 5 \end{pmatrix}$$

$$b = \begin{pmatrix} 5 \\ 18 \\ 9 \end{pmatrix}$$

Step 1: factor A

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 9 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 & 3 \\ 9 & 4 & 10 \\ 6 & -1 & 5 \end{pmatrix}$$

$$R_2 - 3R_1 \rightarrow R_2$$

$$R_3 - 2R_1 \rightarrow R_3$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & -3 & -1 \end{pmatrix}$$

$$R_3 + 3R_2 \rightarrow R_3$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & -3 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$

L

U

$$\begin{pmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b & c & 1 \end{pmatrix}$$

Step 2: solve for Ux

$$Ax = b$$

$$L(Ux) = b$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & -3 & 1 \end{pmatrix} (Ux) = \begin{pmatrix} 5 \\ 18 \\ 9 \end{pmatrix}$$

Front Solve

$$\text{Row 1} \quad y_1 = 5$$

$$\text{Row 2} \quad 3(5) + y_2 = 18$$

$$y_2 = 3$$

$$\text{Row 3} \quad 2 \cdot (5) - 3(3) + y_3 = 9$$

$$y_3 = 8$$

Step 3: solve for x

$$Ux = \begin{pmatrix} 5 \\ 3 \\ 8 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 1 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 5 \\ 3 \\ 8 \end{pmatrix}$$

Back solve

$$\text{Row 3} \quad 2x_3 = 8$$

$$x_3 = 4 \text{ etc.}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ u & 5 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 8 \end{pmatrix}$$

2×3 3×1 2×1

$$x_1 + 2x_2 + 3x_3 = 7$$

$$4x_1 + 5x_2 + 6x_3 = 8$$

Back to our regularly scheduled...

Adjoints!

We can use determinants to find A^{-1} .

Let $A = (a_{ij})$ be an $n \times n$ matrix.

$$\text{Define } c_{ij} = (-1)^{i+j} \det(A_{ij})$$

= the cofactor of the entry a_{ij}

Then define the adjoint of A as

$$\text{adj}(A) = (c_{ji}) = (c_{ij})^t$$

$$\text{Then } A^{-1} = \left(\frac{1}{\det(A)} \right) \text{adj}(A)$$

Example Find $\begin{pmatrix} 1 & 0 & 5 \\ 1 & 1 & 0 \\ 3 & 2 & 6 \end{pmatrix}^{-1}$ using the adjoint.

First find cofactors: cofactor matrix $\begin{pmatrix} 6 & -6 & -1 \\ 10 & -9 & -2 \\ -5 & 5 & 1 \end{pmatrix}$

$$\text{adj}(A) = \begin{pmatrix} 6 & 10 & -5 \\ -6 & -9 & 5 \\ -1 & -2 & 1 \end{pmatrix}$$

$$\det(A) = 1$$

$$\text{Thus } \begin{pmatrix} 1 & 0 & 5 \\ 1 & 1 & 0 \\ 3 & 2 & 6 \end{pmatrix}^{-1} = \begin{pmatrix} 6 & 10 & -5 \\ -6 & -9 & 5 \\ -1 & -2 & 1 \end{pmatrix} \quad (\text{check!})$$

CRAMER'S Rule

Suppose we want to solve $Ax = b$.

Write $A_i(b)$ to be the matrix A with the i^{th} column replaced by b .

$$\text{Then } x_i = \frac{\det(A_i(b))}{\det(A)}$$

Example $x_1 - x_2 = 1$
 $x_2 + 2x_3 = 2$
 $2x_1 + 3x_3 = 3$

$$\left(\begin{array}{ccc|c} 1 & -1 & 0 & 1 \\ 0 & 1 & 2 & 2 \\ 2 & 0 & 3 & 3 \end{array} \right)$$

$$\det(A) = (1)(2) + (1)(-4) = -1$$

$$\det(A_1(b)) = \det \begin{pmatrix} 1 & -1 & 0 \\ 2 & 1 & 2 \\ 3 & 0 & 3 \end{pmatrix} = 3 + 0 = 3$$

$$\det A_2(b) = \det \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 2 & 3 & 3 \end{pmatrix} = (1)(0) - (1)(-4) = 4$$

$$\det(A_3(b)) = \det \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & 2 \\ 2 & 0 & 3 \end{pmatrix} = (1)(3) + (2)(-3) = -3$$

So Cramer's Rule says $x_1 = \frac{3}{-1} = -3$
 $x_2 = \frac{4}{-1} = -4$
 $x_3 = \frac{-3}{-1} = 3$

Kramer's Rule

Let A be an invertible $n \times n$ matrix.

Consider the system of linear equations below:

$$Ax =$$



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Then for each $i=1, \dots, n$,

$$x_i = \frac{\det \begin{bmatrix} a_{1,1} & \dots & a_{1,i-1} & a_{1,i+1} & \dots & a_{1,n} \\ \vdots & & \vdots & \vdots & & \vdots \\ a_{n,1} & \dots & a_{n,i-1} & a_{n,i+1} & \dots & a_{n,n} \end{bmatrix}}{\det A}$$

Exercise 5B

Let a, e, k, m, n, r, s be nonzero constants and let

$$A = \begin{bmatrix} k/r & 2k/s & 0 & 0 & -k/r & -k/n \\ -1 & 0 & 0 & 0 & 1 & r/n \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 2e/s & 0 & 0 & -e/n \\ 0 & 0 & 0 & 0 & 0 & r/n \end{bmatrix}$$

Using Kramer's Rule, solve the linear system

$$Ax = K,$$

where $K = [k \ r \ a \ m \ e \ r]^T$.

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Theorem If A^{-1} exists, then $A^{-1} = \left(\frac{1}{\det(A)}\right) \text{adj}(A)$

Proof We want to show that $A \left(\left(\frac{1}{\det(A)}\right) \text{adj}(A)\right) = I$

OR $A \text{adj}(A) = \det(A) I$

looking at LHS: $(a_{ij})(c_{ij}) := (b_{ij})$

where $b_{ij} = a_{i1}c_{1j} + a_{i2}c_{2j} + \dots + a_{in}c_{nj}$

Case I $i=j$ Then $b_{ii} = \det(A)$

Case II $i \neq j$ Then b_{ij} is the determinant of the matrix obtained by replacing row j with row i (calculated then at row j).

Since this matrix would then have 2 identical

i $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$
 j $\begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$

rows, its determinant is zero.

Therefore $LHS = \det(A) I$ \square

