

If $\begin{pmatrix} x \\ y \end{pmatrix}$ is a vector in \mathbb{R}^2 , then the set of vectors perpendicular to $\begin{pmatrix} x \\ y \end{pmatrix}$ is $\left\{ k \begin{pmatrix} -y \\ x \end{pmatrix} \mid k \in \mathbb{R} \right\}$

(5) How to prove a set of vectors is lin ind?

Assume $c_1 v_1 + c_2 v_2 + \dots + c_r v_r = 0$

Then prove $c_1 = 0, c_2 = 0, \dots, c_r = 0$

Ex Prove $\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \end{pmatrix} \right\}$ is lin ind.

Ans Suppose $c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} = 0$

$$\Rightarrow c_1 + c_2 = 0$$

$$2c_1 + 3c_2 = 0$$

$$\Rightarrow \dots \Rightarrow c_1 = 0, c_2 = 0 \quad \square$$

(6) How to prove a set of vectors is lin dep?

Find a non trivial lin combination that equals zero

Ex Prove $\left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} \right\}$ is lin dep.

Ans

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \square$$

Chapter 7 (continued)

Cayley Hamilton Theorem If $p(x) = \det(A - xI)$ is the characteristic polynomial of a matrix A , then $p(A) = 0$.

proof Consider $\text{adj}(A - xI)$.

Each entry of $\text{adj}(A - xI)$ is a determinant of an $(n-1) \times (n-1)$ submatrix of $(A - xI)$. Thus each entry is a polynomial of x of degree $\leq n-1$.

$$\text{Suppose } A - xI = \begin{pmatrix} 2-x & 3 & 9 \\ 4 & 5-x & 8 \\ 6 & 7 & 10-x \end{pmatrix}$$

Thus $\text{adj}(A - xI)$ can be expressed as

$$\text{adj}(A - xI) = x^{n-1} B_{n-1} + x^{n-2} B_{n-2} + \dots + x B_1 + B_0$$

Idem

$$\begin{pmatrix} x^2 & x^2+x+1 \\ 2x+1 & 0 \end{pmatrix} = x^2 \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} + x \begin{pmatrix} 0 & 1 \\ 2 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Next let

$$\det(A - xI) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

Now Recall that $(A - xI) \left[\frac{\text{adj}(A - xI)}{\det(A - xI)} \right] = I$ ← $(A - xI)^{-1}$

$$(A - xI) \text{adj}(A - xI) = \det(A - xI) I$$

$$\Rightarrow (A - xI) [x^{n-1} B_{n-1} + x^{n-2} B_{n-2} + \dots + x B_1 + B_0] = (a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0) I$$

Then, matching coefficients for powers of x :

$$x^n : A^n (-B_{n-1}) = a_n I$$

$$x^{n-1} : A^{n-1} (A B_{n-1} - B_{n-2}) = a_{n-1} I$$

$$x^{n-2} : A^{n-2} (A B_{n-2} - B_{n-3}) = a_{n-2} I$$

⋮

$$x^1 : A (A B_1 - B_0) = a_1 I$$

$$x^0 : A B_0 = a_0 I$$

Then adding all of these together, the RHS is

$$a_n A^n + a_{n-1} A^{n-1} + a_{n-2} A^{n-2} + \dots + a_1 A + a_0 I = p(A)$$

and the LHS is

$$-A^n B_{n-1} + (A^n B_{n-1} - A^{n-1} B_{n-2}) + (A^{n-1} B_{n-2} - A^{n-2} B_{n-3}) + \dots + (A^2 B_1 - A B_0) + A B_0 = 0$$

□

An example with complex eigenvalues:

Let $A = \begin{pmatrix} 1 & -5 \\ 1 & -1 \end{pmatrix}$

Then $\det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & -5 \\ 1 & -1-\lambda \end{pmatrix} = (1-\lambda)(-1-\lambda) + 5 = \lambda^2 + 4$

So the eigen values are $\pm 2i$.

Find eigenvectors

$$\lambda = 2i \quad \begin{pmatrix} 1-2i & -5 \\ 1 & -1-2i \end{pmatrix} \quad R_1 - (1-2i)R_2$$
$$\begin{pmatrix} 0 & 0 \\ 1 & -1-2i \end{pmatrix}$$

Back solve $x_2 = t$

$$x_1 = (1+2i)t$$

$$\text{eigenspace } \{ t(1+2i, 1) \mid t \in \mathbb{R} \}$$

etc (A is diagonalizable over \mathbb{C})

Ch 8 Linear Transformations

In this course, "transformation" is another word for "function."

In this chapter, we will study functions from vector spaces to vector spaces.

Defn ① A transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is called a linear transformation if there is an $m \times n$ real matrix A so that

$$T(x) = y \iff Ax = y$$

② In this case, the matrix A is called the standard matrix of T .

Example $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 1 & 0 & -2 \\ 2 & 1 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix}$

Definition A linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is called a linear operator if $n=m$.

Examples The zero matrix is the standard matrix for $T(x)=0$

The Identity matrix is the standard matrix for $T(x)=x$

Lemma Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation, and let $\langle e_1, \dots, e_n \rangle$ be the standard basis for \mathbb{R}^n .

Then the standard matrix for T is

$$A = \begin{pmatrix} T(e_1) & T(e_2) & \dots & T(e_n) \end{pmatrix}$$

(where each $T(e_i)$ is a column matrix)

proof Suppose $A = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix}$

Then $T(e_i) = Ae_i = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \end{pmatrix}$ ith position

$= i^{\text{th}}$ column of A \square

Interlude Linear Operators in \mathbb{R}^2

Using the lemma, if T is the reflection across the x-axis,

then $T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

and $T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$

then $A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

What if T is a dilation ^{by k} in the x-coordinate?

$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} k \\ 0 \end{pmatrix}$

$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

So $A = \begin{pmatrix} k & 0 \\ 0 & 1 \end{pmatrix}$

and all of our other examples from before...

Elementary matrices?

| A | Geometric Result of A |
|--|-------------------------|
| $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ | Reflection across $x=y$ |
| $\begin{pmatrix} k & 0 \\ 0 & 1 \end{pmatrix}$ | } dilations |
| $\begin{pmatrix} 1 & 0 \\ 0 & k \end{pmatrix}$ | |
| $\begin{pmatrix} 1 & k \\ 0 & 1 \end{pmatrix}$ | |
| $\begin{pmatrix} 1 & 0 \\ k & 1 \end{pmatrix}$ | |

Since every invertible matrix is the finite product of elem matrices, then

Prop Every invertible linear operator in \mathbb{R}^2 is the product of shears, dilations + reflections across $x=y$.

Exerc of \mathbb{R}^2 interlude //

Lemma If $T_1: \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $T_2: \mathbb{R}^m \rightarrow \mathbb{R}^p$ are linear transformations, then so is $T_2 \circ T_1$.

Proof Suppose A_1 is the standard matrix for T_1 ,

and that A_2 is the standard matrix for T_2 .

$$\text{then } (T_2 \circ T_1)(x) = T_2(T_1(x)) = T_2(A_1 x) = A_2(A_1 x) = (A_2 A_1)x$$

Thus $A_2 A_1$ is the standard matrix for $T_2 \circ T_1$ \square

Definition ① A function $f: X \rightarrow Y$ is one-to-one (or injective) if
($\forall x_1, x_2 \in X$) ($f(x_1) = f(x_2) \Rightarrow x_1 = x_2$)

② A function $f: X \rightarrow Y$ is onto (or surjective) if
for all $y \in Y$, there exists $x \in X$ so that $f(x) = y$

②a Equivalently, $f: X \rightarrow Y$ is onto if $\text{Range}(f) = Y$.

Proposition Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear operator. Then TFAE:

① The standard matrix of T is invertible

② T is one-to-one.

③ T is onto.

